

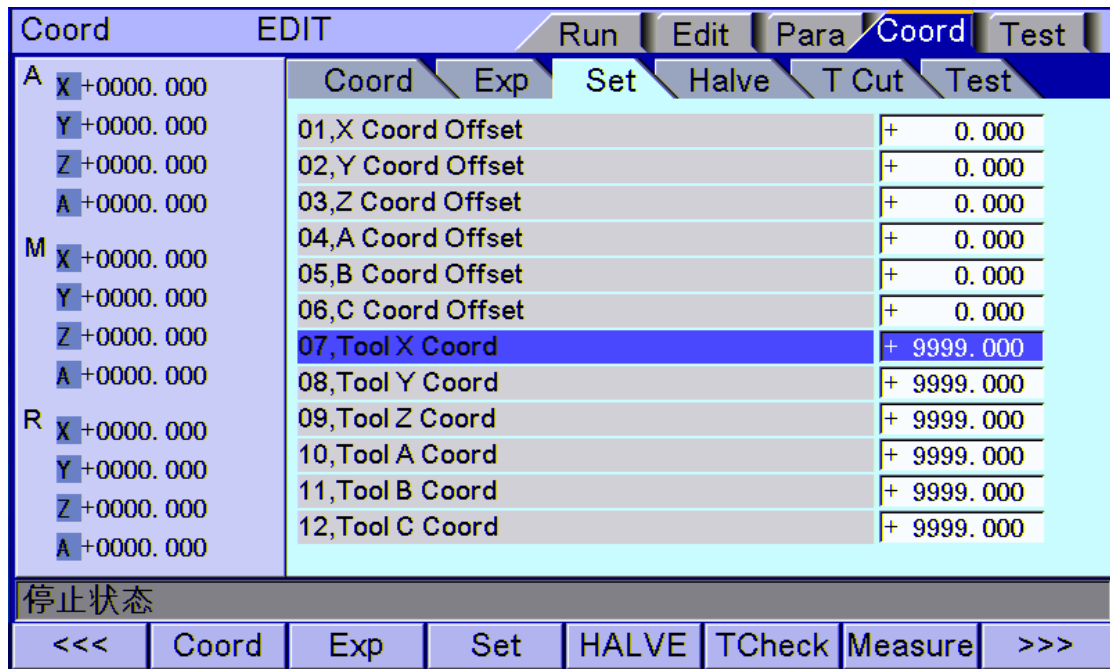
IO para		EDIT	Run	Edit	Para	Coord	Test
001, Tool Checking signal In	IN (05)	015, VFD 1 Level Output	=====				
002, Tool Safe Signal In	=====	016, VFD 2 Level Output	=====				
003, Tool Changer Out	=====	017, VFD 3 Level Output	=====				
004, Tool Changer Dustproof C	=====	018, Spindle CW Output	OUT (00)				
005, Tool Changer Dustproof In	=====	019, Spindle CCW Output	OUT (01)				
006, Tool Limit Input	=====	020, Spindle2 CW Output	=====				
007, Tool Blow Output	=====	021, Spindle2 CCW Output	=====				
008, Spi Alarm Check In	=====	022, Transducer Alarm Rest O	=====				
009, Transducer Alarm Check	=====	023, Spindle Blow Output	=====				
010, Servo Spi ready input	=====	024, Spindle Brake Output	=====				
011, Servo Spi stop input	=====	025, Servo Spi En Output	=====				
012, Servo Spi zero speed input	=====	026, Servo Spi Stop Output	=====				
013, Servo Spi speed reach input	=====	027, Servo Spi Pulse Output	=====				
014, VFD 0 Level Output	=====	028, sv Spi Rigid tapping output	=====				
001, Tool Checking signal In range:0 ~ 65535 macroaddr:10000							
<<<	General	Axis	Manage	Tool	Spindle	Port	>>>

3 , the coordinates - > coordinates - > 7 on the knife X coordinate .

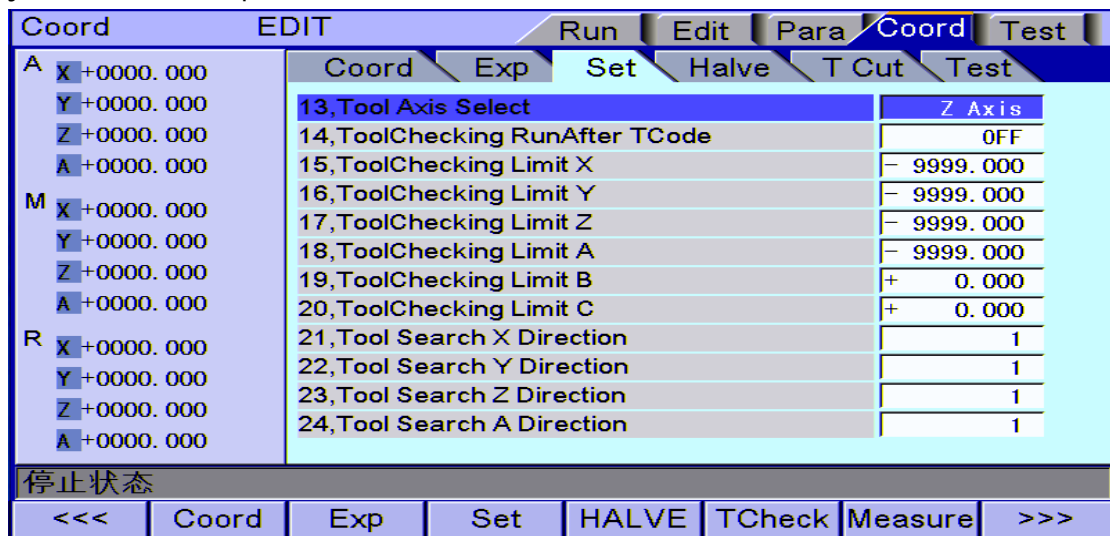
8 Y coordinates on the knife

9 on the knife Z coordinates

10. coordinate ----- A knife set on the knife mounting location , pay attention to the parameters of the machine coordinate value to the Z-axis of the knife as an example , such as X for 200, Y for 300 Z 100 , the system scans when the knife after , the knife axis Z -axis to move fast machine coordinate 100 , then quickly moved to the X and Y axis machine coordinate at 200 and 300 of the Z -axis signal to start scanning for the knife , which parameter applies only to fixed installation in case the machine at a location for the activities of the knife block knife way , on the knife is a knife at any point , you can set this parameter to 9999 , when the knife system scan directly to the current point on the knife signal.



4 , coordinates - > coordinates - > 13 on the knife shaft election signs ----- set to start on the knife on the knife shaft , for example, is enabled by default Z Axis Z -axis of the knife A Axis. Press the left arrow key and right arrow keys to switch to the A -axis on the knife , you can select the parameter after the cursor .



5 , coordinates - > coordinates -> 1.X coordinate offset

2.Y coordinate system offsets

3.Z coordinate system offsets

4.A coordinate system offset -----

Set the work piece coordinate system and the point of the knife offset , for example, to the point of a knife machine coordinate -100 , coordinate offset of 10 , the work piece coordinate system zero point of $-100 + 10 = -90$ at the work piece zero , the system the point of the knife scanner machine coordinate plus the offset to the work piece zero

position , for a fixed installation on the knife , by measuring this parameter is generally functional test out . First, choose a knife after the work piece coordinate system by measuring function , the system will signal to scan on the knife , put in place after the scanning machine coordinates minus the work piece zero point of the knife at the machine coordinates , the result set of offsets , this parameter can also be entered manually , knife blocks for knives, knife block thickness can be entered into this parameter , in general, the work piece origin point at the top of the knife offset is positive , the work piece points above the knife point on partial shift amount is negative (such as knife blocks) .

Coord		EDIT		Run	Edit	Para	Coord	Test
A	X	+0000.000		Coord	Exp	Set	Halve	T Cut
	Y	+0000.000						Test
	Z	+0000.000						
	A	+0000.000						
M	X	+0000.000						
	Y	+0000.000						
	Z	+0000.000						
	A	+0000.000						
R	X	+0000.000						
	Y	+0000.000						
	Z	+0000.000						
	A	+0000.000						
				01,X Coord Offset			+	0.000
				02,Y Coord Offset			+	0.000
				03,Z Coord Offset			+	0.000
				04,A Coord Offset			+	0.000
				05,B Coord Offset			+	0.000
				06,C Coord Offset			+	0.000
				07,Tool X Coord			+	9999.000
				08,Tool Y Coord			+	9999.000
				09,Tool Z Coord			+	9999.000
				10,Tool A Coord			+	9999.000
				11,Tool B Coord			+	9999.000
				12,Tool C Coord			+	9999.000
停止状态								
<<<		Coord	Exp	Set	HALVE	TCheck	Measure	>>>

6 , coordinates - > coordinates - > 15 on the knife machine limit ... 21 on the knife search direction ----- limit set on the machine and coordinate the knife on the knife . search direction , a direction of the search is negative , 0 is a positive direction search .

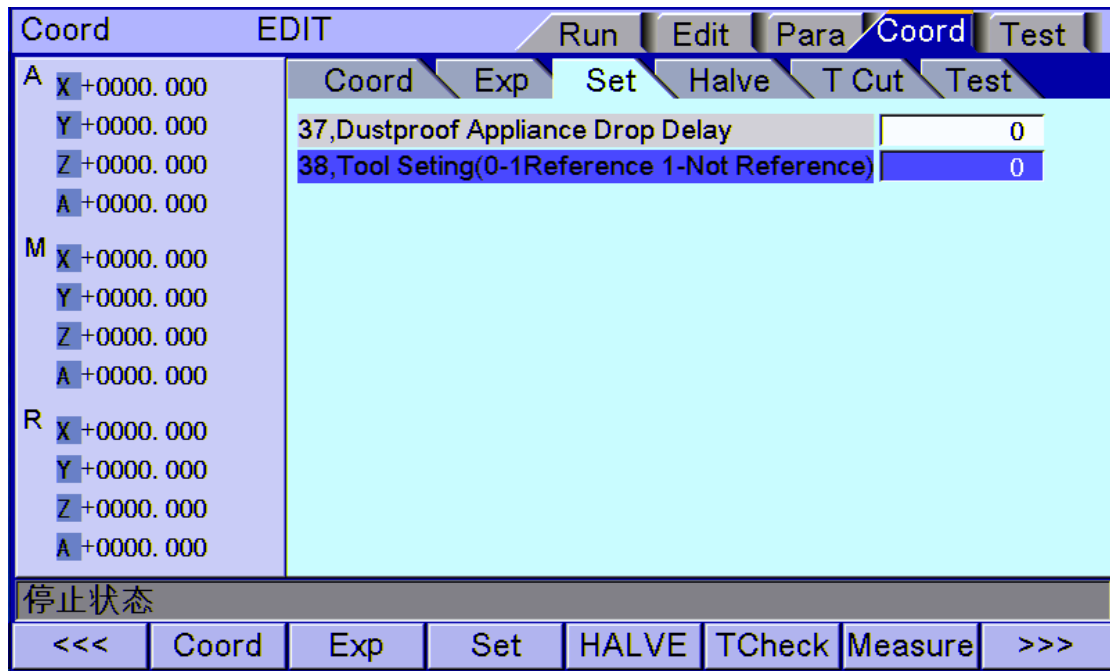
Coord		EDIT		Run	Edit	Para	Coord	Test
A	X	+0000.000		Coord	Exp	Set	Halve	T Cut
	Y	+0000.000						Test
	Z	+0000.000						
	A	+0000.000						
M	X	+0000.000						
	Y	+0000.000						
	Z	+0000.000						
	A	+0000.000						
R	X	+0000.000						
	Y	+0000.000						
	Z	+0000.000						
	A	+0000.000						
				13,Tool Axis Select				Z Axis
				14,ToolChecking RunAfter TCode				OFF
				15,ToolChecking Limit X			-	9999.000
				16,ToolChecking Limit Y			-	9999.000
				17,ToolChecking Limit Z			-	9999.000
				18,ToolChecking Limit A			-	9999.000
				19,ToolChecking Limit B			+	0.000
				20,ToolChecking Limit C			+	0.000
				21,Tool Search X Direction				1
				22,Tool Search Y Direction				1
				23,Tool Search Z Direction				1
				24,Tool Search A Direction				1
停止状态								
<<<		Coord	Exp	Set	HALVE	TCheck	Measure	>>>

7 , coordinates - > coordinates - > 28 ----- scanning speed on the knife set the system searches for the search speed knife signal , the default is 1000mm / min, such as setting the Z axis of the knife. when , Z -axis negative direction began to search for the knife signal on to 1000mm / min speed of the search until after the knife sensed signal , the system is

switched relocation scan for slow scan speed on the knife signal.

Coord		EDIT		Run	Edit	Para	Coord	Test
A	X	+0000.000		Coord	Exp	Set	Halve	T Cut
	Y	+0000.000						Test
	Z	+0000.000						
	A	+0000.000						
M	X	+0000.000		25,Tool Search B Direction				0
	Y	+0000.000		26,Tool Search C Direction				0
	Z	+0000.000		27,Auto Add Offset En				OFF
	A	+0000.000		28,Tool Speed				1000
R	X	+0000.000		29,Tool Start Using En				OFF
	Y	+0000.000		30,Tool X Safe Pos			+	0.000
	Z	+0000.000		31,Tool Y Safe Pos			+	0.000
	A	+0000.000		32,Tool Z Safe Pos			+	0.000
	X	+0000.000		33,Tool A Safe Pos			+	0.000
	Y	+0000.000		34,Tool B Safe Pos			+	0.000
	Z	+0000.000		35,Tool C Safe Pos			+	0.000
	A	+0000.000		36,Tool Safe Check En				OFF
停止状态								
<<<		Coord	Exp	Set	HALVE	TCheck	Measure	>>>

8 , coordinates - > coordinates - > 38 ----- after the knife way to set the system for handling the knife scanner after the end of the knife the way , the scan is completed a non-benchmark knife will work piece datum position calculation is set to the coordinate system , such as work piece zero coordinate scanned -90 , set the system will coordinate values of -90 to the coordinate system settings in the Z-axis (Z -axis of the knife) , the set of coordinate system is a coordinate set in the currently selected coordinate system , in the program by calling the coordinate system instructions to achieve length compensation , 0 is the base of the knife blade mode settings after scanning tool will compensate for the value of the 1st correction the length of the compensation amount which , for example, the 2nd time on the knife , the system value is set to put the knife correction amount of the 2nd length compensation value , and then call the G43 H2 achieve length compensation , the 1st knife meant as a reference tool in the program is in the measurement coordinate offset when the amount to be measured to the 1st blade , the correction amount of the compensation amount is generally 1 to 0 .



On the knife using steps and trouble shootings:

1 According to the system requirements , the modified parameters , system diagnostics to diagnose the input signal screen , active level is correct, the diagnostic screens such as IN5 red light indicates a detected low as 0 , bright green light that detects high level 1, and then confirm the level of the corresponding parameters are correct , when setting error scanning speed and direction will not normal.

2. After the scan is completed , the work piece by moving the machine to zero , to confirm the compensation value is correct.

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